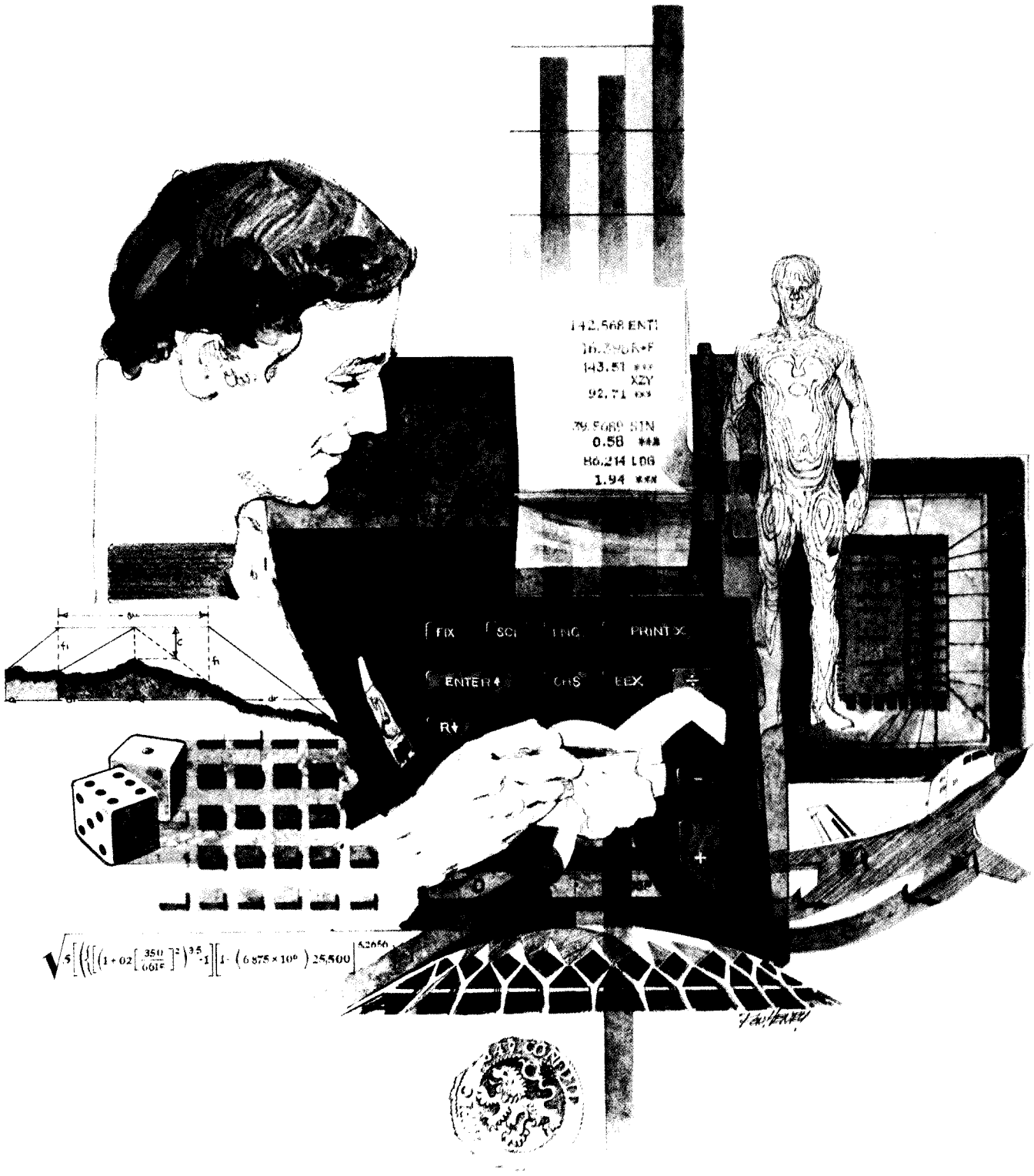


HEWLETT-PACKARD

HP-67/HP-97

Users' Library Solutions

Geometry



INTRODUCTION

In an effort to provide continued value to its customers, Hewlett-Packard is introducing a unique service for the HP fully programmable calculator user. This service is designed to save you time and programming effort. As users are aware, Programmable Calculators are capable of delivering tremendous problem solving potential in terms of power and flexibility, but the real genie in the bottle is program solutions. HP's introduction of the first handheld programmable calculator in 1974 immediately led to a request for program **solutions** — hence the beginning of the HP-65 Users' Library. In order to save HP calculator customers time, users wrote their own programs and sent them to the Library for the benefit of other program users. In a short period of time over 5,000 programs were accepted and made available. This overwhelming response indicated the value of the program library and a Users' Library was then established for the HP-67/97 users.

To extend the value of the Users' Library, Hewlett-Packard is introducing a unique service—a service designed to save you time and money. The Users' Library has collected the best programs in the most popular categories from the HP-67/97 and HP-65 Libraries. These programs have been packaged into a series of low-cost books, resulting in substantial savings for our valued HP-67/97 users.

We feel this new software service will extend the capabilities of our programmable calculators and provide a great benefit to our HP-67/97 users.

A WORD ABOUT PROGRAM USAGE

Each program contained herein is reproduced on the standard forms used by the Users' Library. Magnetic cards are not included. The Program Description I page gives a basic description of the program. The Program Description II page provides a sample problem and the keystrokes used to solve it. The User Instructions page contains a description of the keystrokes used to solve problems in general and the options which are available to the user. The Program Listing I and Program Listing II pages list the program steps necessary to operate the calculator. The comments, listed next to the steps, describe the reason for a step or group of steps. Other pertinent information about data register contents, uses of labels and flags and the initial calculator status mode is also found on these pages. Following the directions in your HP-67 or HP-97 **Owners' Handbook and Programming Guide**, "Loading a Program" (page 134, HP-67; page 119, HP-97), key in the program from the Program Listing I and Program Listing II pages. A number at the top of the Program Listing indicates on which calculator the program was written (HP-67 or HP-97). If the calculator indicated differs from the calculator you will be using, consult Appendix E of your **Owner's Handbook** for the corresponding keycodes and keystrokes converting HP-67 to HP-97 keycodes and vice versa. No program conversion is necessary. The HP-67 and HP-97 are totally compatible, but some differences do occur in the keycodes used to represent some of the functions.

A program loaded into the HP-67 or HP-97 is not permanent—once the calculator is turned off, the program will not be retained. You can, however, permanently save any program by recording it on a blank magnetic card, several of which were provided in the Standard Pac that was shipped with your calculator. Consult your **Owner's Handbook** for full instructions. A few points to remember:

The Set Status section indicates the status of flags, angular mode, and display setting. After keying in your program, review the status section and set the conditions as indicated before using or permanently recording the program.

REMEMBER! To save the program permanently, **clip** the corners of the magnetic card once you have recorded the program. This simple step will protect the magnetic card and keep the program from being inadvertently erased.

As a part of HP's continuing effort to provide value to our customers, we hope you will enjoy our newest concept.

TABLE OF CONTENTS

189

SINE PLATE SOLUTIONS	1
Coordinates of a point, position and slope of an inclined hole.	
This program, with the aid of commonly available dowel pins, measuring tools, (in the case of the sine plate, obviously a sine plate and height blocks), will aid in accurately finding angles, including holes and coordinates of points.	
V NOTCHES AND LONG RADII	8
This program, together with commonly available dowel pins and height gages, will accurately determine the position and angles of "V" grooves or notches. With the same tools, long radii are accurately measured.	
INTERNAL AND EXTERNAL TAPERS	14
This program, used with commonly available dowel pins, height bases, and balls, will accurately determine the position and angle of both external and internal tapers.	
POINTS OF TANGENCY WITH CIRCLES AND ARCS	20
These programs will accurately locate points of tangency between straight lines and arcs, between straight lines and a circle, and between two circles and a straight line.	
LINE-LINE INTERSECTION/GRID POINTS	26
This card will calculate the point of intersection of two lines and the Cartesian coordinates of points in other systems.	
POINTS ON A STRAIGHT LINE	33
This program calculates the coordinates of equidistant points on a straight line.	
GRID OF POINTS: CALCULATES ALL POINTS	37
This program calculates the X and Y coordinates, all the points of a grid.	
GRID OF POINTS: CALCULATE DISCRETE POINTS	42
This program complements "Grid of Points: Calculate all Points". It allows the calculation of specified points of grid.	
TANGENT CIRCLE TO TWO STRAIGHT LINES WITH A GIVEN RADIUS	46
This problem calculates the X and Y coordinates of the center of a circle with a given radius. This circle being tangent to two given straight lines. In the more general case, there are four center solutions to this problem.	
DISTANCE BETWEEN LINES IN SPACE	52
Given two lines, each defined by any two points, program calculates shortest distance between the two lines. (This program was written to determine the clearance between electrical distribution circuits and guy wires or supporting structures.)	

Program Description I

Program Title Sine Plate Solutions,
 Coordinate of a Point, Position and Slope of an Inclined Hole
Contributor's Name David Stedman
Address 15950 Oakridge Road
City Morgan Hill **State** California **Zip Code** 97330

Program Description, Equations, Variables

This program, with the aid of commonly available dowel pins, measuring tools,
 (in the case of the sine plate, obviously a sine plate and height blocks), will
 aid in accurately finding angles, including holes and coordinates of points.

Operating Limits and Warnings

All angular output is in decimal degrees. Use the H.MS conversions on the
 calculator to convert back and forth between degrees, minutes and seconds
 and decimal degrees.

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

NEITHER HP NOR THE CONTRIBUTOR MAKES ANY EXPRESS OR IMPLIED WARRANTY OF ANY KIND WITH REGARD TO THIS PROGRAM MATERIAL, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. NEITHER HP NOR THE CONTRIBUTOR SHALL BE LIABLE FOR INCIDENTAL OR CONSEQUENTIAL DAMAGES IN CONNECTION WITH OR ARISING OUT OF THE FURNISHING, USE OR PERFORMANCE OF THIS PROGRAM MATERIAL.

Program Description II

Sketch(es) Solution for Finding Coordinates of a Point

Given: a, b, d and e, determine x and y

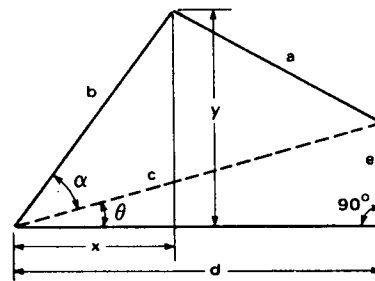
$$c^2 = d^2 + e^2$$

$$\cos \alpha = \frac{b^2 + c^2 - a^2}{2bc}$$

$$\tan \theta = \frac{e}{d}$$

$$x = b \cos (\alpha + \theta)$$

$$y = b \sin (\alpha + \theta)$$



Sample Problem(s) Given a = 1.290" d = 2.000"
 b = 1.470" e = .568"

Solution(s) Keystrokes

1.29 [↑] 1.47 [↑] 2. [↑] .568 [A]

⏏ x = *** ,8679", Y = *** 1.186"

Reference(s) _____

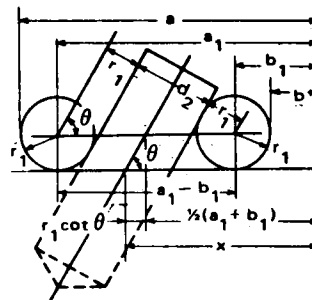
Sketch(es)

Solution for Finding the Location and Angle of an Inclined Hole

Given: a , b , r , and d_2 , determine θ and x

$$\sin \theta = \frac{2r_1 + d_2}{a_1 - b_1}$$

$$x = \frac{1}{2}(a_1 + b_1) + r_1 \cot \theta$$



Sample Problem(s)

Given $a = 1.630''$

$$r_1 = .200''$$
$$b = .260''$$
$$d_7 = .4375''$$

Solution(s)	Keystrokes
-------------	------------

1.63 [↑] .26 [↑] .2 [↑] .4375 [A]

C ; *** Θ = *** 59.7007, χ = *** 1.0619"

Reference(s)

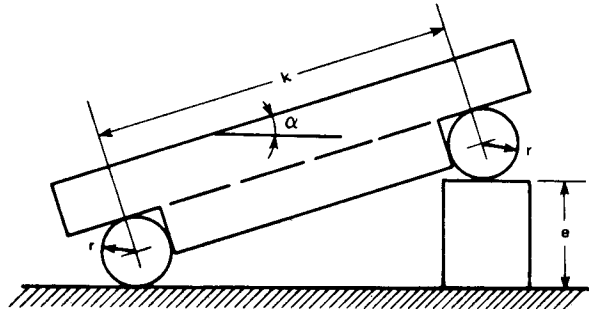
Program Description II

Sketch(es)

Given: e and K , determine α

$$\sin \alpha = \frac{e}{K}$$

Interchangeable Solutions for Work with a
Sine Bar



Sample Problem(s)

Given: Sine Bar Length $[K] = 5."$

Sample #1

Gage Blocks Height $[e] = 1.7101$

Find angle α

Solution(s)

Keystrokes 5[↑] 1.7101[f] [D]

$$\alpha = 20.0000^\circ$$

OR

Sample #2

Given: Sine Bar Length $[K] = 10"$

Angle $[\alpha] = 32.12^\circ$

Find Necessary Gage Block Height

Keystrokes 10[↑] 32.12 [f][E]

$$e = 5.3169"$$

Sample #3

Given: Sine Bar Length $[K] = 5"$

Angle $[\alpha] = 21^\circ 12' 41"$

Find Necessary Gage Block Height

Keystrokes 5[↑] 21.1241[f] [H+] [f] [E]

$$e = 1.8090"$$

5

[illegible]

97 Program Listing I

STEP	KEY ENTRY	KEY CODE	COMMENTS	STEP	KEY ENTRY	KEY CODE	COMMENTS
001	*LBLA	21 11	Initialize for either coordinates of a point or an inclined hole.	057	RCL4	36 04	
002	CLRG	16-53		058	+	-55	
003	ST04	35 04		059	RCL1	36 01	
004	R↓	-31		060	RCL3	36 03	
005	ST03	35 03		061	-	-45	
006	R↓	-31		062	ST05	35 05	
007	ST02	35 02		063	RCL2	36 02	
008	R↓	-31		064	RCL3	36 03	
009	ST01	35 01		065	+	-55	
010	RTN	24		066	ST06	35 06	
011	*LBLB	21 12	Find the coordinates of a point.	067	-	-45	
012	RCL4	36 04		068	÷	-24	
013	X ²	53		069	SIN ⁻¹	16 41	
014	RCL3	36 03		070	ST07	35 07	
015	X ²	53		071	SPC	16-11	
016	+	-55		072	PRTX	-14	
017	ST05	35 05		073	RCL7	36 07	
018	RCL2	36 02		074	TAN	43	
019	X ²	53		075	1/X	52	
020	+	-55		076	RCL3	36 03	
021	RCL1	36 01		077	x	-35	"θ"
022	X ²	53		078	RCL5	36 05	
023	-	-45		079	RCL6	36 06	
024	RCL5	36 05		080	+	-55	
025	√X	54		081	2	02	
026	RCL2	36 02		082	÷	-24	
027	x	-35		083	+	-55	
028	2	02		084	PRTX	-14	
029	x	-35		085	SPC	16-11	
030	÷	-24		086	RTN	24	
031	COS ⁻¹	16 42	"x"	087	*LBLd	21 16 14	Initialize sine bar (find alpha).
032	ST06	35 06		088	CLRG	16-53	
033	RCL4	36 04		089	ST02	35 02	
034	RCL3	36 03		090	R↓	-31	
035	÷	-24		091	ST01	35 01	
036	TAN ⁻¹	16 43		092	RTN	24	
037	ST07	35 07		093	*LBLD	21 14	
038	RCL6	36 06		094	RCL2	36 02	
039	+	-55		095	RCL1	36 01	
040	ST08	35 08		096	÷	-24	
041	COS	42	"y"	097	SIN ⁻¹	16 41	Find α.
042	RCL2	36 02		098	SPC	16-11	
043	x	-35		099	PRTX	-14	
044	SPC	16-11		100	SPC	16-11	
045	PRTX	-14		101	RTN	24	
046	RCL8	36 08		102	*LBLd	21 16 15	
047	SIN	41		103	CLRG	16-53	
048	RCL2	36 02		104	ST02	35 02	
049	x	-35		105	R↓	-31	
050	PRTX	-14		106	ST01	35 01	
051	SPC	16-11		107	RTN	24	Initialize sine bar (find height).
052	RTN	24		108	*LBLD	21 15	
053	*LBLC	21 13		109	RCL2	36 02	
054	RCL3	36 03		110	SIN	41	
055	2	02		111	RCL1	36 01	
056	x	-35		112	x	-35	
REGISTERS							
0	1 Used	2 Used	3 Used	4 Used	5 Used	6 Used	7 Used
S0	S1	S2	S3	S4	S5	S6	S7
A	B	C	D	E	I		

7

[illegible]

Program Description I

Program Title V Notches and Long Radii

Contributor's Name David Stedman

Address 15950 Oakridge Road

City Morgan Hill

State California

Zip Code 95037

Program Description, Equations, Variables

This program, together with commonly available dowel pins and height gages, will accurately determine the position and angles of "V" grooves or notches. With the same tools, long radii are accurately measured.

Operating Limits and Warnings

All angular output is in decimal degrees. Use the H.MS conversion on the calculator to convert back and forth between degrees, minutes and seconds and decimal degrees.

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

NEITHER HP NOR THE CONTRIBUTOR MAKES ANY EXPRESS OR IMPLIED WARRANTY OF ANY KIND WITH REGARD TO THIS PROGRAM MATERIAL, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. NEITHER HP NOR THE CONTRIBUTOR SHALL BE LIABLE FOR INCIDENTAL OR CONSEQUENTIAL DAMAGES IN CONNECTION WITH OR ARISING OUT OF THE FURNISHING, USE OR PERFORMANCE OF THIS PROGRAM MATERIAL.

Program Description II

9

Sketch(es)

Given: a, b, c, d, r_1 and r_2 ,
determine x, y, α and β

$$\tan \phi = \frac{b_1 - a_1}{d_1 - c_1}$$

$$\overline{O_1 O_2} = \frac{d_1 - c_1}{\cos \phi}$$

$$\sin \theta = \frac{r_2 - r_1}{\overline{O_1 O_2}}$$

$$\overline{O O_1} = \frac{r_1}{\sin \theta}$$

$$x = a_1 - \overline{O O_1} \sin \phi$$

$$y = c_1 - \overline{O O_1} \cos \phi$$

$$\alpha = 90^\circ + \phi - \theta$$

$$\beta = 90^\circ - \phi - \theta$$

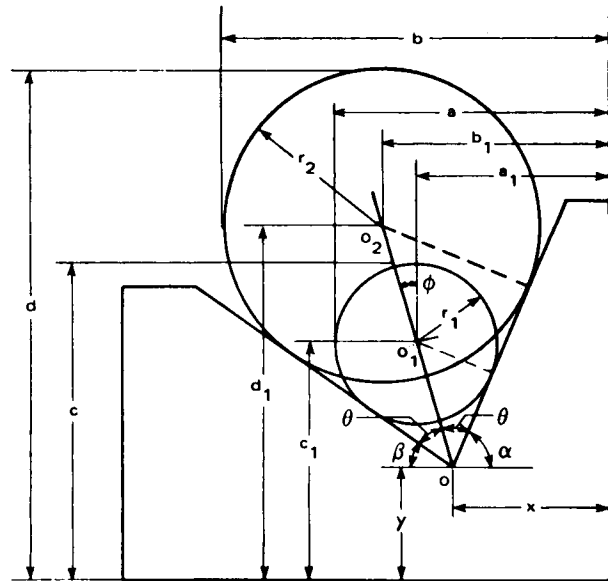
Special case for $\phi = 0$, then:

$$\alpha = \beta$$

$$\overline{O_1 O_2} = d_1 - c_1$$

$$\sin \theta = \frac{r_2 - r_1}{d_1 - c_1}$$

$$y = c_1 - \frac{r_1}{\sin \theta}$$



Solution for "V" Notch

Sample #1 Given: $a = 1.500''$ $d = 2.800''$

$b = 2.125''$ $r_1 = .4375''$

$c = 1.750''$ $r_2 = .875''$

Keystrokes 1.5[+], 2.125[+], 1.75[+], 2.8[A], .4375[+], .875[f] [A]

$\triangleright$; $x = .875''$; $y = .700''$; $\alpha = 63.942^\circ$; $\beta = 29.901^\circ$

Sample #2 [where $\phi = \text{zero}$]

$a = 1.500''$

$d = 2.900''$

$b = 1.900''$

$r_1 = .500''$

$c = 1.800''$

$r_2 = .900''$

Keystrokes 1.5[+], 1.9[+], 1.8[+], 2.9[A], .5[+], .9[f] [A]

$\triangleright$; 111111111, $x = 1.000''$; $y = .425''$; $\alpha = \beta = 55.150^\circ$

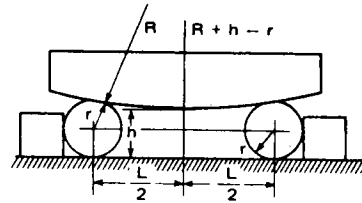
Program Description II

Sketch(es)

Given: L, r and h, determine R

$$(R + r)^2 = (R + h - r)^2 + \left(\frac{1}{2}L\right)^2$$

$$R = \frac{L^2}{8(2r - h)} - \frac{h}{2}$$



Solution for Long Radii, Convex Arcs

Sample #1 Given: L = 1.000"

r = .15625"

h = .270"

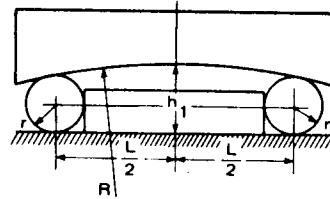
Keystrokes

1.[+].15625[+] .27[C] ►; R = 2.8062"

Given: L, r and h₁, determine R

$$(R - r)^2 = (R - h_1 + r)^2 + \left(\frac{1}{2}L\right)^2$$

$$R = \frac{L^2}{8(h_1 - 2r)} + \frac{h_1}{2}$$



Solution for Long Radii, Concave Arcs

Sample #2 Given: L = 1.300"

r = .15625"

h = .378"

Keystrokes

1.3[+] .15625[+] .378[C] ►; R = 3.4142"

Reference(s)

97 Program Listing I

STEP	KEY ENTRY	KEY CODE	COMMENTS	STEP	KEY ENTRY	KEY CODE	COMMENTS
001	*LBLA	21 11	Initialize V notch.	057	X $\div$ Y	-41	
002	ST04	35 04		058	=	-24	
003	R $\downarrow$	-31		059	ST04	35 04	
004	ST03	35 03		060	RCL1	36 01	
005	R $\downarrow$	-31		061	RCL7	36 07	
006	ST02	35 02		062	SIN	41	
007	R $\downarrow$	-31		063	RCL4	36 04	
008	ST01	35 01		064	x	-35	
009	R $\downarrow$	-31		065	-	-45	
010	RTN	24		066	SPC	16-11	
011	*LBLA	21 16 11		067	PRTX	-14	
012	ST06	35 06		068	RCL3	36 03	
013	R $\downarrow$	-31		069	RCL7	36 07	
014	ST05	35 05		070	COS	42	
015	RTN	24		071	RCL4	36 04	
016	*LBLB	21 12	V notch solution.	072	x	-35	
017	RCL3	36 03		073	-	-45	
018	RCL5	36 05		074	PRTX	-14	
019	-	-45		075	9	09	
020	ST03	35 03		076	0	00	
021	RCL1	36 01		077	RCL7	36 07	
022	RCL5	36 05		078	+	-55	
023	-	-45		079	RCL2	36 02	
024	ST01	35 01		080	SIN $^{-1}$	16 41	
025	RCL2	36 02		081	ST02	35 02	
026	RCL6	36 06		082	-	-45	
027	-	-45		083	PRTX	-14	
028	ST02	35 02		084	9	09	
029	RCL4	36 04		085	0	00	
030	RCL6	36 06		086	RCL7	36 07	
031	-	-45		087	-	-45	
032	ST04	35 04		088	RCL2	36 02	
033	RCL2	36 02		089	-	-45	
034	RCL1	36 01		090	PRTX	-14	
035	-	-45		091	RTN	24	
036	RCL4	36 04		092	*LBL1	21 01	a = β special case.
037	RCL3	36 03		093	SPC	16-11	
038	-	-45		094	1	01	
039	ST08	35 08		095	1	01	
040	=	-24		096	1	01	
041	TAN $^{-1}$	16 43		097	1	01	
042	X=0?	16-43		098	1	01	
043	GT01	22 01		099	1	01	
044	ST07	35 07		100	1	01	
045	COS	42		101	1	01	
046	RCL8	36 08		102	1	01	
047	X $\div$ Y	-41		103	1	01	
048	=	-24		104	PRTX	-14	
049	ST08	35 08		105	RCL1	36 01	
050	RCL6	36 06		106	PRTX	-14	
051	RCL5	36 05		107	RCL6	36 06	
052	-	-45		108	RCL5	36 05	
053	X $\div$ Y	-41		109	-	-45	
054	=	-24		110	RCL8	36 08	
055	ST02	35 02		111	=	-24	
056	RCL5	36 05		112	ST00	35 00	

REGISTERS

0	1	2	3	4	5	6	7	8	9
Used	Used	Used	Used	Used	Used	Used	Used	Used	
S0	S1	S2	S3	S4	S5	S6	S7	S8	S9
A	B	C	D	E	I				

97 Program Listing II

13

STEP	KEY ENTRY	KEY CODE	COMMENTS	STEP	KEY ENTRY	KEY CODE	COMMENTS
113	RCL5	36 05		169	SPC	16-11	
114	X $\div$ Y	-41		170	PRTX	-14	
115	$\div$	-24		171	SPC	16-11	
116	RCL3	36 03		172	RTN	24	
117	X $\div$ Y	-41					
118	-	-45					
119	PRTX	-14					
120	9	09					
121	0	00					
122	RCL0	36 00					
123	SIN $^{-1}$	16 41					
124	-	-45		180			
125	PRTX	-14					
126	SPC	16-11					
127	RTN	24					
128	*LBLC	21 13					
129	STO3	35 03	Initialize long				
130	R $\downarrow$	-31	radii arc.				
131	STO2	35 02					
132	R $\downarrow$	-31					
133	STO1	35 01					
134	RTN	24		190			
135	*LBLD	21 14					
136	RCL1	36 01	Convex long radii				
137	X 2	53	solution.				
138	RCL2	36 02					
139	2	02					
140	x	-35					
141	RCL3	36 03					
142	-	-45					
143	8	08					
144	x	-35		200			
145	$\div$	-24					
146	RCL3	36 03					
147	2	02					
148	$\div$	-24					
149	-	-45					
150	SPC	16-11					
151	PRTX	-14					
152	SPC	16-11					
153	RTN	24					
154	*LBL E	21 15		210			
155	RCL1	36 01	Concave long radii				
156	X 2	53	solution.				
157	RCL3	36 03					
158	RCL2	36 02					
159	2	02					
160	x	-35					
161	-	-45					
162	8	08					
163	x	-35					
164	$\div$	-24		220			
165	RCL3	36 03					
166	2	02					
167	$\div$	-24					
168	+	-55					

LABELS					FLAGS	SET STATUS		
A	B	C	D	E	0	FLAGS	TRIG	DISP
Ini V notch	Solve	Long Radii	Convex	Concave		ON OFF		
a	b	c	d	e	1	0 ☐ ☒	DEG ☒	FIX ☒
0	1 $\phi = 0$	2	3	4	2	1 ☐ ☒	GRAD ☐	SCI ☐
5	6	7	8	9	3	2 ☐ ☒	RAD ☐	ENG ☐
						3 ☐ ☒		n <u>3</u>

Program Description I

Program Title Internal and External Tapers

Contributor's Name David Stedman

Address 15950 Oakridge Road

City Morgan Hill

State California

Zip Code 95037

Program Description, Equations, Variables

This program, used with commonly available dowel pins, height bases, and balls, will accurately determine the position and angle of both external and internal tapers.

Operating Limits and Warnings

All angular output is in decimal degrees which can be converted to degrees, minutes and seconds with the $\rightarrow$ H.MS function.

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

NEITHER HP NOR THE CONTRIBUTOR MAKES ANY EXPRESS OR IMPLIED WARRANTY OF ANY KIND WITH REGARD TO THIS PROGRAM MATERIAL, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. NEITHER HP NOR THE CONTRIBUTOR SHALL BE LIABLE FOR INCIDENTAL OR CONSEQUENTIAL DAMAGES IN CONNECTION WITH OR ARISING OUT OF THE FURNISHING, USE OR PERFORMANCE OF THIS PROGRAM MATERIAL.

Program Description II

Sketch(es)

Given: b, c, d, r_1 and r_2 , determine C, D, ϕ and R_1

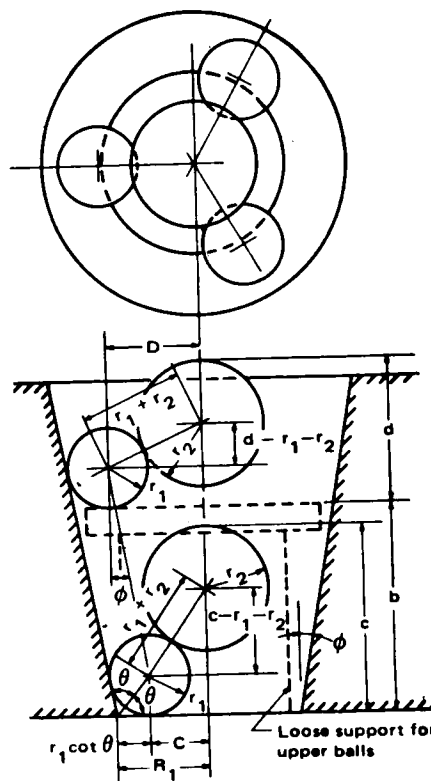
$$C^2 = 2c(r_1 + r_2) - c^2$$

$$D^2 = 2d(r_1 + r_2) - d^2$$

$$\tan \theta = \frac{D - C}{b}$$

$$2\theta = 90^\circ + \phi$$

$$R_1 = C + r_1 \cot \theta$$



Solution for Finding Internal Taper

Sample #1 Given: $b = 1.150''$ $r_1 = .21875''$
 $c = 1.050''$ $r_2 = .34375''$
 $d = .800''$

Keystrokes

1.15[+], 1.05[+], .8[+], .21875[A], .34375[f][A]

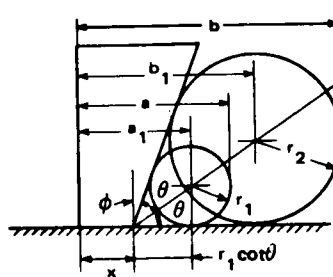
▶; $c = .2806''$, $d = .5099''$, $\phi = 11.2753^\circ$, $\theta = 50.6377^\circ$ $R_1 = .4601''$

Given: a, b, r_1 and r_2 , determine x and ϕ

$$\tan \theta = \frac{r_2 - r_1}{b_1 - a_1}$$

$$\phi = 90^\circ - 2\theta$$

$$x = a_1 - r_1 \cot \theta$$



Solution for Finding External Tapers, Case #1

Sample #2 Given: $a = .820''$ $r_1 = .21875''$
 $b = 1.430''$ $r_2 = .46875''$

Keystrokes

.82[+] 1.43[+] .21875[+] .46875[A]

▶; $\phi = 20.444^\circ$, $x = .28625''$

Program Description II

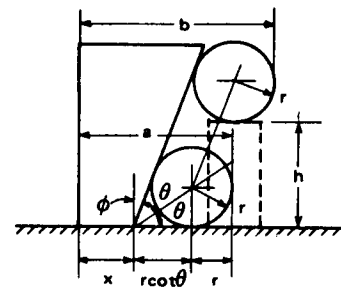
Sketch(es)

Given: a, b, r and h, determine x and ϕ

$$\tan 2\theta = \frac{h}{b-a}$$

$$\phi = 90 - 2\theta$$

$$x = a - r - r \cot \theta$$



Solution for Finding External Tapers, Case #2

Sample #3 Given: a = .830" r = .21875"
b = 1.070" h = .5625"

Keystrokes

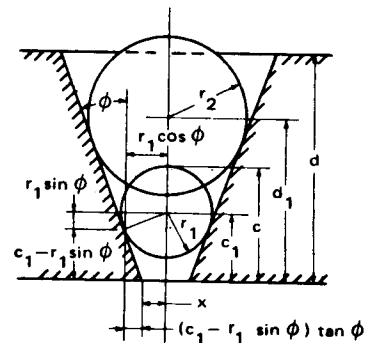
.83[+] 1.07[+] .21875[+] .5625[A]

▷; $\phi = 23.106^\circ$, x = .28008"

Given: c, d, r_1 and r_2 , determine x and ϕ

$$\sin \phi = \frac{r_2 - r_1}{d_1 - c_1}$$

$$x = \frac{r_1}{\cos \phi} - c_1 \tan \phi$$



Solution for Finding External Tapers Case #3

Sample #4 Given: c = .625" r_1 = .250"
d = 1.250" r_2 = .4375"

Keystrokes

.625[+] 1.25[+] .25[+] .4375[A]

▷; $\phi = 25.3769^\circ$, x = .09882"

17

[illegible]

97 Program Listing I

STEP	KEY ENTRY	KEY CODE	COMMENTS	STEP	KEY ENTRY	KEY CODE	COMMENTS
001	*LBLA	21 11	Store values	057	TAN	43	Calculate R_1 .
002	ST04	35 04		058	1/X	52	
003	R4	-31		059	RCL4	36 04	
004	ST03	35 03		060	x	-35	
005	R4	-31		061	RCL6	36 06	
006	ST02	35 02		062	+	-55	
007	R4	-31		063	ST09	35 09	
008	ST01	35 01		064	PRTX	-14	
009	RTN	24		065	SPC	16-11	
010	*LBLA	21 16 11		066	RTN	24	
011	ST05	35 05	Store r_2 .	067	*LBLC	21 13	Case 1, external taper.
012	RTN	24	Case 1, internal taper.	068	GSB1	23 01	
013	*LBLB	21 12		069	TAN ⁻¹	16 43	
014	RCL5	36 05		070	ST05	35 05	
015	RCL4	36 04		071	2	02	
016	+	-55		072	x	-35	
017	ST07	35 07		073	9	09	
018	RCL2	36 02		074	0	00	
019	2	02		075	X ² Y	-41	
020	x	-35		076	-	-45	
021	x	-35	Calculate "C"	077	SPC	16-11	Calculate ϕ
022	RCL2	36 02		078	PRTX	-14	
023	ENT [†]	-21		079	RCL5	36 05	
024	x	-35		080	TAN	43	
025	-	-45		081	1/X	52	
026	JX	54		082	RCL3	36 03	
027	ST06	35 06		083	x	-35	
028	SPC	16-11		084	RCL7	36 07	
029	PRTX	-14		085	X ² Y	-41	
030	RCL7	36 07		086	-	-45	
031	RCL3	36 03	Calculate "D"	087	PRTX	-14	Calculate x
032	2	02		088	SPC	16-11	
033	x	-35		089	RTN	24	
034	x	-35		090	*LBLD	21 14	
035	RCL3	36 03		091	RCL4	36 04	
036	ENT [†]	-21		092	RCL2	36 02	
037	x	-35		093	RCL1	36 01	
038	-	-45		094	-	-45	
039	JX	54		095	÷	-24	
040	ST07	35 07		096	TAN ⁻¹	16 43	Case 2, external taper.
041	PRTX	-14	Calculate ϕ	097	ST05	35 05	
042	RCL7	36 07		098	9	09	
043	RCL6	36 06		099	0	00	
044	-	-45		100	X ² Y	-41	
045	RCL1	36 01		101	-	-45	
046	÷	-24		102	SPC	16-11	
047	TAN ⁻¹	16 43		103	PRTX	-14	
048	ST07	35 07		104	RCL1	36 01	Calculate x
049	PRTX	-14		105	RCL3	36 03	
050	9	09	Calculate θ	106	-	-45	
051	0	00		107	LSTX	16-63	
052	+	-55		108	RCL5	36 05	
053	2	02		109	2	02	
054	÷	-24		110	÷	-24	
055	ST08	35 08		111	TAN	43	
056	PRTX	-14		112	1/X	52	

REGISTERS

0	1	2	3	4	5	6	7	8	9
	b or a	c or b	d or r_1	r_1 or r_2	r_2 or used c / used D, ϕ			θ or NA	R_1 or NA
S0	S1	S2	S3	S4	S5	S6	S7	S8	S9
A	B	C	D	E	I				

[illegible]

Program Description I

Program Title Points of Tangency With Circles and Arcs

Contributor's Name David Stedman

Address 15950 Oakridge Road

City Morgan Hill

State California

Zip Code 95057

Program Description, Equations, Variables

These programs will accurately locate points of tangency between straight lines and arcs, between straight lines and a circle, and between two circles and a straight line.

Operating Limits and Warnings

All angular outputs are in decimal degrees, $\rightarrow$ H.MS may be used to convert to degrees, minutes, and seconds.

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

NEITHER HP NOR THE CONTRIBUTOR MAKES ANY EXPRESS OR IMPLIED WARRANTY OF ANY KIND WITH REGARD TO THIS PROGRAM MATERIAL, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. NEITHER HP NOR THE CONTRIBUTOR SHALL BE LIABLE FOR INCIDENTAL OR CONSEQUENTIAL DAMAGES IN CONNECTION WITH OR ARISING OUT OF THE FURNISHING, USE OR PERFORMANCE OF THIS PROGRAM MATERIAL.

Program Description II

21

Sketch(es)

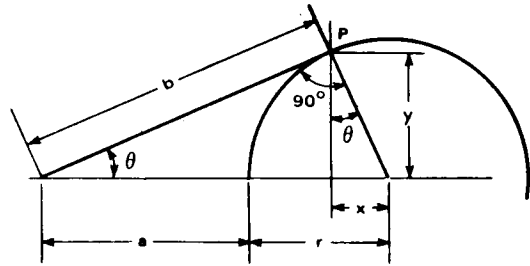
Given: a and r , determine x and y

$$b^2 = (a + r)^2 - r^2$$

$$\sin \theta = \frac{r}{a + r} = \frac{y}{b} = \frac{x}{r}$$

$$x = \frac{r^2}{a + r}$$

$$y = \frac{br}{a + r}$$



Solution for Finding Point of Tangency With an Arc Figure 1

Sample Problem(s) Sample #1 Given: $a = 1.125''$

$$r = .750''$$

Keystrokes 1.125[+] .75[+] [A]

$$\triangleright; x = .3000'', y = .6874''$$

- Optional -

$$[f] \triangleright; b = 1.7185, \theta = 23.5782^\circ$$

Given: b , c and r , determine x_1 and y_1

$$a = \sqrt{b^2 + c^2} - r$$

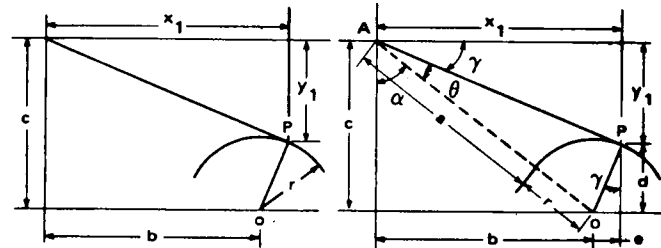
$$\sin \theta = \frac{r}{a + r}$$

$$\tan \alpha = \frac{b}{c}$$

$$\gamma = 90^\circ - \theta - \alpha$$

$$e = r \sin \gamma, \text{ then } x_1 = b + e$$

$$d = r \cos \gamma, \text{ then } y_1 = c - d$$



Solution for Finding Points of Tangency with A Circle

Sample #2 Given: $b = 1.175''$, $c = .930''$ $r = .405''$

Figure 2

Keystrokes 1.175[+] .93[+] .405[A]

$$\triangleright; x_1 = 1.3312'', y_1 = .5563''$$

- Optional -

$$[f] c; a = 1.0935'', \theta = 15.6803^\circ, \alpha = 51.6388^\circ$$

Reference(s)

Program Description II

Sketch(es) Given: a , b , r_1 and r_2 , determine x_1 , y_1 , x_2 and y_2

$$c = \sqrt{a^2 + b^2}$$

$$\tan \theta = \frac{b}{a}$$

$$\sin \phi = \frac{r_2 - r_1}{c}$$

$$x_1 = r_1 \sin (\theta + \phi)$$

$$y_1 = r_1 \cos (\theta + \phi)$$

$$x_2 = r_2 \sin (\theta + \phi)$$

$$y_2 = b + r_2 \cos (\theta + \phi)$$

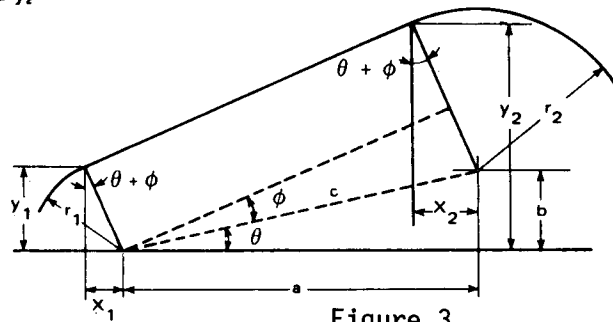


Figure 3

Sample Problem(s) Solution for Finding Points of Tangency with Two Circles

Sample #3 Given: $a = 1.950''$ $r_1 = .500''$
 $b = .4375''$ $r_2 = .880''$

Keystrokes 1.95[+] .4375[+] .5[+] .88[A]

[D]; $x_1 = .2002$, $y_1 = .4582$, $x_2 = .3524$, $y_2 = 1.2439$

- Optional -

[f] [D]; $c = 1.9985''$, $\theta = 12.6454^\circ$, $\phi = 10.9612^\circ$

Solution(s)

Reference(s)

23

[illegible]

97 Program Listing I

STEP	KEY ENTRY	KEY CODE	COMMENTS	STEP	KEY ENTRY	KEY CODE	COMMENTS
001	*LBLA	21 11	Start by storing values.	057	X ²	53	Circle.
002	CLRG	16-53		058	+	-55	
003	ST04	35 04		059	JX	54	
004	R↓	-31		060	RCL4	36 04	
005	ST03	35 03		061	-	-45	
006	R↓	-31		062	ST05	35 05	
007	ST02	35 02		063	RCL4	36 04	
008	R↓	-31		064	ENT↑	-21	
009	ST01	35 01		065	ENT↑	-21	
010	RTN	24		066	RCL5	36 05	
011	*LBLB	21 12	Calculate point of tangency with an arc.	067	+	-55	
012	RCL4	36 04		068	÷	-24	
013	RCL3	36 03		069	SIN ⁻¹	16 41	
014	+	-55		070	ST06	35 06	
015	X ²	53		071	RCL2	36 02	
016	RCL4	36 04		072	RCL3	36 03	
017	X ²	53		073	÷	-24	
018	-	-45		074	TAN ⁻¹	16 43	
019	JX	54		075	ST07	35 07	
020	ST05	35 05		076	9	09	
021	RCL4	36 04		077	0	00	
022	ENT↑	-21		078	RCL6	36 06	
023	RCL3	36 03		079	-	-45	
024	+	-55		080	RCL7	36 07	
025	÷	-24		081	-	-45	
026	COS ⁻¹	16 42		082	ST08	35 08	
027	ST06	35 06		083	SIN	41	
028	RCL4	36 04		084	RCL4	36 04	
029	X ²	53		085	x	-35	
030	LSTX	16-63		086	RCL2	36 02	
031	RCL3	36 03	"x"	087	+	-55	"x"
032	+	-55		088	SPC	16-11	
033	÷	-24		089	PRTX	-14	
034	SPC	16-11		090	RCL8	36 08	
035	PRTX	-14		091	COS	42	
036	RCL5	36 05		092	RCL4	36 04	
037	RCL4	36 04		093	x	-35	
038	x	-35		094	RCL3	36 03	
039	LSTX	16-63		095	X ² Y	-41	
040	RCL3	36 03		096	-	-45	
041	+	-55	"y"	097	PRTX	-14	"y"
042	÷	-24		098	RTN	24	
043	PRTX	-14		099	*LBLc	21 16 13	
044	SPC	16-11		100	RCL5	36 05	
045	RTN	24		101	PRTX	-14	
046	*LBLb	21 16 12		102	RCL6	36 06	
047	RCL5	36 05		103	PRTX	-14	
048	PRTX	-14		104	RCL7	36 07	
049	RCL6	36 06		105	PRTX	-14	
050	PRTX	-14		106	RTN	24	
051	SPC	16-11	Calculate point of tangency with a	107	*LBLD	21 14	Calculate point of tangency with two circles.
052	RTN	24		108	RCL1	36 01	
053	*LBLC	21 13		109	RCL2	36 02	
054	RCL2	36 02		110	→P	34	
055	X ²	53		111	ST05	35 05	
056	RCL3	36 03		112	RCL2	36 02	

REGISTERS

0	0	1	Input	2	Input	3	Input	4	Input	5	Used	6	Used	7	Used	8	Used	9	0
S0		S1		S2		S3		S4		S5		S6		S7		S8		S9	
A	0	B	0	C	0	D	0	E	0	F	0	G	0	H	0	I	0	J	0

25

[illegible]

Program Description I

Program Title Line-Line Intersection/Grid Points

Contributor's Name David Stedman

Address 15950 Oakridge Road

City Morgan Hill

State Ca.

Zip Code 95037

Program Description, Equations, Variables

This card will calculate the point of intersection of two lines and the Cartesian coordinates of points in other systems.

See page two for equations and sketch.

Operating Limits and Warnings

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

NEITHER HP NOR THE CONTRIBUTOR MAKES ANY EXPRESS OR IMPLIED WARRANTY OF ANY KIND WITH REGARD TO THIS PROGRAM MATERIAL, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. NEITHER HP NOR THE CONTRIBUTOR SHALL BE LIABLE FOR INCIDENTAL OR CONSEQUENTIAL DAMAGES IN CONNECTION WITH OR ARISING OUT OF THE FURNISHING, USE OR PERFORMANCE OF THIS PROGRAM MATERIAL.

Program Description II

EQUATIONS For both programs, the user specifies the angle from horizontal to lines in the problem. Slope will be converted to angle by the relation $\theta = \tan^{-1}(\text{slope})$. Given two points (x_1, y_1) and (x_2, y_2) on the line, the angle is

$$\theta = \tan^{-1} \left(\frac{y_2 - y_1}{x_2 - x_1} \right)$$

Line-Line Intersection

(x, y) = Coordinates of point of intersection

(x_1, y_1) = Coordinates of point on line one

(x_2, y_2) = Coordinates of point on line two

θ_1 = Angle from horizontal to line one

θ_2 = Angle from horizontal to line two

Grid Points

(x_0, y_0) = Coordinates of 0, 0 grid point

h_1, h_2 = Grid system unit vectors

θ_1 = Angle to h_1 unit vector

θ_2 = Angle to h_2 unit vector

(x_{ij}, y_{ij}) = Coordinates of i, j grid point

Equations:

Line-Line Intersection

$$x = \frac{x_1 \tan \theta_1 - x_2 \tan \theta_2 + y_2 - y_1}{\tan \theta_1 - \tan \theta_2}$$

$$y = y_1 + (x - x_1) \tan \theta_1$$

Grid Points

$$x_{ij} = x_0 + j\Delta x_1 + i\Delta x_2$$

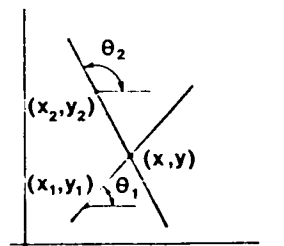
$$y_{ij} = y_0 + j\Delta y_1 + i\Delta y_2$$

$$\Delta x_1 = h_1 \cos \theta_1$$

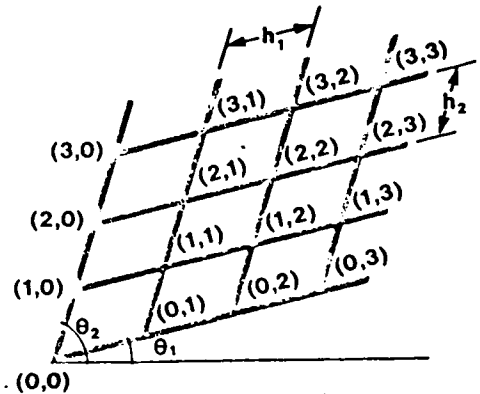
$$\Delta y_1 = h_1 \sin \theta_1$$

$$\Delta x_2 = h_2 \cos \theta_2$$

$$\Delta y_2 = h_2 \sin \theta_2$$



Line-Line Intersection



Grid Points

Program Description II

Sketch(es)

Sample Problem(s)

Example 1. Find the point of intersection of two lines passing through (10,20) (40,30) and (-10,30) (50,10).

$10 \uparrow 20 \uparrow 40 \uparrow 30$ f A 10 CHS $\uparrow 30 \uparrow 50 \uparrow 10$ f B $\rightarrow 15.00, 21.67$

Example 2. Find the intersection of a line through (0,0) with slope 2.8 and the line with equation $x = 4.5$.

$4.5 \uparrow 0 \uparrow 0 \uparrow 2.8$ f E $\rightarrow 12.60$

Example 3. For a grid with its origin at (1,1) and vectors 2 and 3 units long at 30 and 90 degrees, respectively, find the cartesian coordinates for the following grid coordinates: (0,0), (1,0), (2,0), (0,1), (0,2), (1,1), (1.5,3).

$1 \uparrow 1 \uparrow 2 \uparrow 3$ C $30 \uparrow 90$ D $0 \uparrow 0$ E $\rightarrow 1.00, 1.00$

$1 \uparrow 0$ E $\rightarrow 1.00, 4.00$

$2 \uparrow 0$ E $\rightarrow 1.00, 7.00$

$0 \uparrow 1$ E $\rightarrow 2.73, 2.00$

$0 \uparrow 2$ E $\rightarrow 4.46, 3.00$

$1 \uparrow 1$ E $\rightarrow 2.73, 5.00$

$1.5 \uparrow 3$ E $\rightarrow 6.20, 8.50$

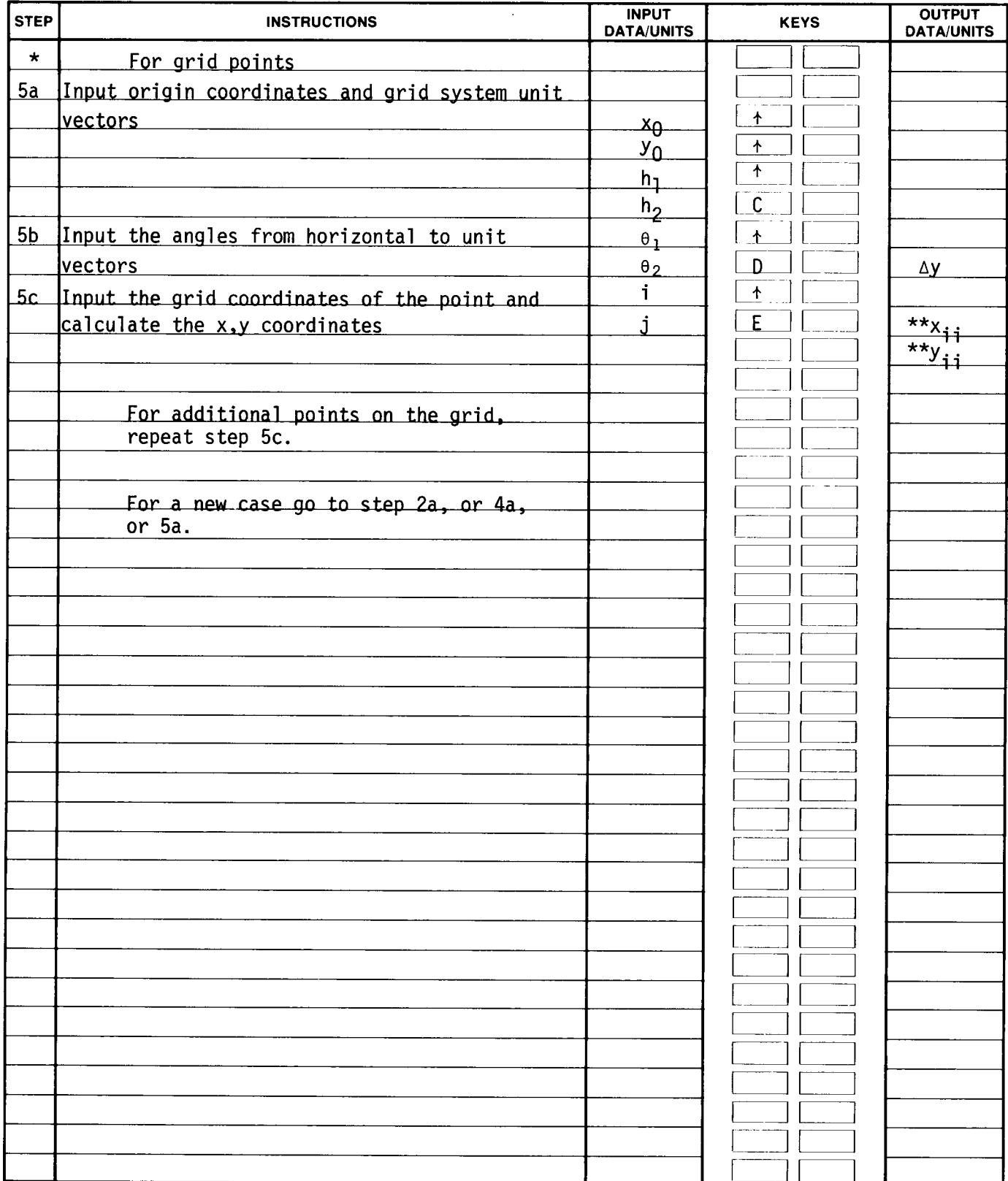
Reference(s)

User Instructions

LINE-LINE INTERSECTION / GRID POINTS

$$x_1+y_1+x_1+y_1 \quad x_2+y_2+x_2+y_2 \quad x_1+y_1+s_1p \quad x_2+y_2+s_1p \quad [x_1]x_1+y_1+s_1p$$
$$x_1, y_1, \theta_1 \quad x_2, y_2, \theta_2 \quad x_0, y_0, h_1, h_2 \quad \theta_1, \theta_2 \quad i \rightarrow j \rightarrow x_{ij}, y_{ij}$$

STEP	INSTRUCTIONS	INPUT DATA/UNITS	KEYS		OUTPUT DATA/UNITS
1	Load side 1 and side 2.				
*	For line-line intersection [no vertical lines]				
2a	Input coordinates of point on line one and angle from horizontal to line	x_1			
		y_1			
		θ_1			
	or				
2b	Input coordinates at two points on line	x_1			
		y_1			
		x_1'			
		y_1'			
	or				
2c	Input coordinates of point on line and slope	x_1			
		y_1			
		slope ₁			
3a	Input coordinates of point on line two and angle from horizontal to the line and calculate coordinates of point of intersection	x_2			
		y_2			
		θ_2			x, y
	or				
3b	Input coordinates at two points on line 2	x_2			
		y_2			
		x_2'			
		y_2'			x, y
3c	Input coordinates of point on line two and slope	x_2			
		y_2			
		slope ₂			x, y
*	For line-line intersection [one vertical line]				
4a	Input x coordinate of vertical line, coordinates of point on line one	x			
		x_1			
		y_1			
	and angle from horizontal to line	θ_1			y
	or				
4b	Input x coordinates of vertical line, coordinates of point on line one and slope of line	x			
		x_1			
		y_1			
		slope			y



97 Program Listing I

31

STEP	KEY ENTRY	KEY CODE	COMMENTS	STEP	KEY ENTRY	KEY CODE	COMMENTS
001	*LBLA	21 16 11		057	PZS	16-51	
002	PZS	16-51		058	*LBLB	21 12	
003	CLRG	16-53		059	TAN	43	
004	ST04	35 04		060	ST04	35 04	
005	R↓	-31		061	XZY	-41	
006	ST03	35 03		062	R↓	-31	
007	R↓	-31		063	x	-35	
008	ST02	35 02		064	R↑	16-31	
009	R↓	-31		065	-	-45	
010	ST01	35 01		066	RCL2	36 02	
011	RCL4	36 04		067	+	-55	
012	RCL2	36 02		068	RCL1	36 01	
013	-	-45		069	RCL3	36 03	
014	RCL3	36 03		070	x	-35	
015	RCL1	36 01		071	-	-45	
016	-	-45		072	RCL4	36 04	
017	÷	-24		073	RCL3	36 03	
018	TAN ⁻¹	16 43		074	-	-45	
019	ST05	35 05		075	÷	-24	
020	RCL1	36 01		076	ST04	35 04	
021	RCL2	36 02		077	PRTX	-14	
022	RCL5	36 05		078	RCL4	36 04	
023	PZS	16-51		079	RCL1	36 01	
024	*LBLA	21 11		080	-	-45	
025	TAN	43		081	RCL3	36 03	
026	ST03	35 03		082	x	-35	
027	R↓	-31		083	RCL2	36 02	
028	ST02	35 02		084	+	-55	
029	R↓	-31		085	R/S	51	
030	ST01	35 01		086	*LBLC	21 13	
031	-	-45		087	ST08	35 08	
032	x	-35		088	R↓	-31	
033	+	-55		089	ST07	35 07	
034	R/S	51		090	R↓	-31	
035	*LBLB	21 16 12		091	ST04	35 04	
036	PZS	16-51		092	R↓	-31	
037	CLRG	16-53		093	ST01	35 01	
038	ST04	35 04		094	R/S	51	
039	R↓	-31		095	*LBLD	21 14	
040	ST03	35 03		096	1	01	
041	R↓	-31		097	→R	44	
042	ST02	35 02		098	RCL8	36 08	
043	R↓	-31		099	x	-35	
044	ST01	35 01		100	ST03	35 03	
045	RCL4	36 04		101	R↓	-31	
046	RCL2	36 02		102	RCL8	36 08	
047	-	-45		103	x	-35	
048	RCL3	36 03		104	ST06	35 06	
049	RCL1	36 01		105	R↓	-31	
050	-	-45		106	1	01	
051	÷	-24		107	→R	44	
052	TAN ⁻¹	16 43		108	RCL7	36 07	
053	ST05	35 05		109	x	-35	
054	RCL1	36 01		110	ST02	35 02	
055	RCL2	36 02		111	R↓	-31	
056	RCL5	36 05		112	RCL7	36 07	

REGISTERS

0	1	2	3	4	5	6	7	8	9
	x_1, x_0	$y_1, \Delta x_1$	$\tan \theta_1, \Delta x_2$	$\tan \theta_2, y_0$	Δy_1	Δy_2	h_1	h_2	Used
S0	S1	S2	S3	S4	S5	S6	S7	S8	S9
	Used	Used	Used	Used	Used				
A	B	C	D	E	I				

97 Program Listing II

STEP	KEY ENTRY	KEY CODE	COMMENTS	STEP	KEY ENTRY	KEY CODE	COMMENTS
113	x	-35		169	R↓	-31	
114	ST05	35 05		170	ST01	35 01	
115	R/S	51		171	RCL4	36 04	
116	*LBL E	21 15		172	TAN ⁻¹	16 43	
117	ST08	35 08		173	ST05	35 05	
118	RCL2	36 02		174	RCL1	36 01	
119	x	-35		175	RCL2	36 02	
120	RCL1	36 01		176	RCL3	36 03	
121	+	-55		177	RCL5	36 05	
122	X↔Y	-41		178	P↔S	16-51	
123	ST07	35 07		179	GTOA	22 11	
124	RCL3	36 03		180	RTN	24	
125	x	-35					
126	+	-55					
127	PRTX	-14					
128	RCL8	36 08					
129	RCL5	36 05					
130	x	-35					
131	RCL4	36 04					
132	+	-55					
133	RCL7	36 07					
134	RCL6	36 06		190			
135	x	-35					
136	+	-55					
137	RTN	24					
138	*LBL c	21 16 13					
139	P↔S	16-51					
140	CLRG	16-53					
141	ST03	35 03					
142	R↓	-31					
143	ST02	35 02					
144	R↓	-31		200			
145	ST01	35 01					
146	RCL3	36 03					
147	TAN ⁻¹	16 43					
148	ST04	35 04					
149	RCL1	36 01					
150	RCL2	36 02					
151	RCL4	36 04					
152	P↔S	16-51					
153	F2?	16 23 02					
154	GTOB	22 12		210			
155	GTOA	22 11					
156	RTN	24					
157	*LBL d	21 16 14					
158	SF2	16 21 02					
159	GTO c	22 16 13					
160	RTN	24					
161	*LBL e	21 16 15					
162	P↔S	16-51					
163	CLRG	16-53					
164	ST04	35 04		220			
165	R↓	-31					
166	ST03	35 03					
167	R↓	-31					
168	ST02	35 02					

LABELS					FLAGS	SET STATUS		
A	B	C	D	E	0	FLAGS	TRIG	DISP
(X↑)X↑+Y↑+P	X ₂ +Y ₂ +θ ₂	X ₀ +Y ₀ +h ₁ +h ₂	θ ₁ +θ ₂	i j X _i ·Y _j		ON OFF		
X ₁ +Y ₁ +X ₁ ↑Y ₁	X ₂ +Y ₂ +X ₂ ↑Y ₂	X ₁ +Y ₁ +slp ₁	X ₂ +Y ₂ +slp ₂	(X↑)X↑ Y↑slp	1	0 ☐ ☒	DEG ☒	FIX ☒
0	1	2	3	4	2 Used	1 ☐ ☒	GRAD ☐	SCI ☐
5	6	7	8	9	3	2 ☐ ☒	RAD ☐	ENG ☐
						3 ☐ ☒		n-2

Program Description I

Program Title Points on a Straight Line

Contributor's Name DAVID STEDMAN

Address 15950 OAKRIDGE ROAD

City MORGAN HILL, State CALIFORNIA Zip Code 95037

Program Description, Equations, Variables THIS PROGRAM CALCULATES THE COORDINATES OF EQUIDISTANT POINTS ON A STRAIGHT LINE.

DATA:

- THE STARTING POINT [CALLED 1]

$$P_1 = [X_1, Y_1]$$

- THE ANGLE OF THE STRAIGHT LINE WITH THE POSITIVE X AXIS: θ_1

- THE DISTANCE BETWEEN TWO CONSECUTIVE POINTS IN THE DIRECTION OF THE STRAIGHT LINE: H

- THE NUMBER OF POINTS N, FOR AUTOMATIC CALCULATION [THE POINT 1 BEING INCLUDED].

POINT P_i IS CALCULATED BY:
$$X_i = X_1 + (i-1) H \cos \theta_1$$
$$Y_i = Y_1 + (i-1) H \sin \theta_1$$

THE AUTO OPTION IS PROVIDED FOR OUTPUT OF THE ORDERED PAIRS $[X_n, Y_n]$ THROUGH PRINT COMMANDS. IF AUTO IS NOT SELECTED, THE VALUES WILL BE OUTPUT ONE AT A TIME BY THE USE OF R/S.

RESULTS: AT YOUR OPTION:

- AUTOMATICALLY INCREMENT i [$i=1,2,\dots,n$] FOR X_i AND Y_i COORDINATES.
- CALCULATE COORDINATES X_i AND Y_i OF ONE POINT i .

NOTE: BECAUSE POINTS CAN BE REQUESTED INDIVIDUALLY IT IS POSSIBLE TO CALCULATE POINTS SUCH AS P_{-1} , P_0 , and P_{-3} etc...CHAINING OF ORDERED PAIRS IS AUTOMATIC AFTER RESULT $[X_1, Y_1]$, Y_1 HAVING BEEN DISPLAYED.

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

NEITHER HP NOR THE CONTRIBUTOR MAKES ANY EXPRESS OR IMPLIED WARRANTY OF ANY KIND WITH REGARD TO THIS PROGRAM MATERIAL, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. NEITHER HP NOR THE CONTRIBUTOR SHALL BE LIABLE FOR INCIDENTAL OR CONSEQUENTIAL DAMAGES IN CONNECTION WITH OR ARISING OUT OF THE FURNISHING, USE OR PERFORMANCE OF THIS PROGRAM MATERIAL.

Program Description II

EXAMPLE : STRAIGHT LINE DESIGNATED BY:

$$P_1 (x_1 = 10, y_1 = 10, \theta = -30^\circ, H = 20)$$

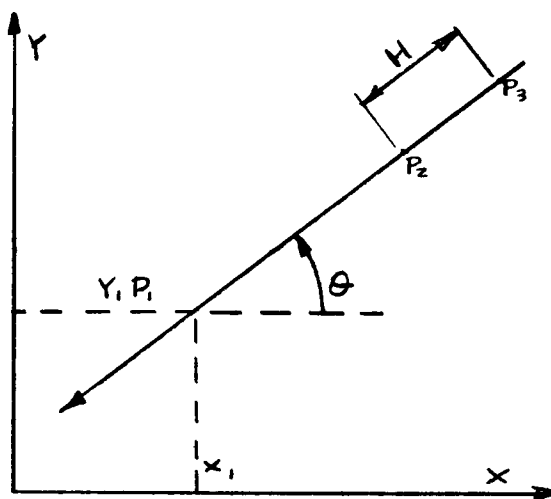
- AUTOMATIC CALCULATION OF 6 POINTS (N=6)

i	1	2	3	4	5	6
x_i	10.0000	27.3205	44.6410	61.9615	79.2820	96.6025
y_i	10.0000	0.0000	-10.0000	-20.0000	-30.0000	-40.0000

- POINT i AT REQUEST:

$$P_0 (i=0), x = -7.321, y = 20.000$$

$$P_{-1} (i=-1), x = -24.641, y = 30.000 \text{ ETC...}$$



10 (↑) 10 (↑) 30 (CHS) (A) 20 (↑) 6 (B) (C)----->1.0000

10.0000

10.0000

etc.

Reference(s)

User Instructions

35

1
POINTS ON A STRAIGHT LINE
2

X_1, Y_1, θ_1
 H, N
 $P_1 \rightarrow P_n$
 $i - P_i$
AUTO?

STEP	INSTRUCTIONS	INPUT DATA/UNITS	KEYS		OUTPUT DATA/UNITS
1	ENTER THE PROGRAM				
2	ENTER POINT 1	X_1			
		Y_1			
	ENTER THE ANGLE OF THE LINE	θ_1			1.0000
3	ENTER THE DISTANCE BETWEEN EACH POINT	H			
	ENTER THE NUMBER OF POINTS	N			
4	- MANUAL MODE -				
	CALCULATE ALL THE POINTS				1.0000
	$i = 1 \dots N$.				X_1
					Y_1
5	DO 5-6-7 UNTIL DISPLAY FLASHES				i
6					X_i
7					Y_i
					FLASH
8	CALCULATE POINT i	i			X_i
					Y_i
9	-AUTO MODE-				1.0000
10	CALCULATE ALL THE POINTS				1.0000
	$i = 1 \dots N$.				X_1
					Y_1
					X_i
					Y_i
	CALCULATOR WILL FLASH ZEROS WHEN PROBLEM IS COMPLETE				FLASH
11	CALCULATE POINT i	i			X_i
					Y_i
	CALCULATOR WILL FLASH ZEROS WHEN FINISHED				FLASH
12	FOR A NEW CASE, RESET DISPLAY GO TO 2				.XXXX

LABELS					FLAGS	SET STATUS		
A X_1, Y_1, θ_1	B H, N	C $P_1 \rightarrow P_n$	D $i - P_i$	E AUTO	0	FLAGS	TRIG	DISP
a X_1, Y_1, θ_1	b	c $P_1 \rightarrow P_n$	d	e	1 AUTO	ON OFF		
0	1	2	3	4	2	0 ☐ ☒	DEG ☒	FIX ☒
						1 ☐ ☒	GRAD ☐	SCI ☐
						2 ☐ ☒	RAD ☐	ENG ☐
5	6	7	8	9	3	3 ☐ ☒		n <u>4</u>

97 Program Listing I

COMMENTS	STEP	KEY ENTRY	KEY CODE	COMMENTS
001 *LBLA 21 11		057 1 01		
002 COS 42		058 - -45		
003 ST06 35 06		059 ST03 35 03		
004 LSTX 16-63		060 RCL6 36 06		
005 SIN 41		061 x -35		
006 ST07 35 07		062 RCL1 36 01		
007 R+ -31		063 + -55		
008 R+ -31		064 ST04 35 04		
009 ST02 35 02		065 F1? 16 23 01		
010 R+ -31		066 GT04 22 04		
011 ST01 35 01		067 *LBL5 21 05		
012 1 01		068 RCL3 36 03		
013 RTN 24		069 RCL7 36 07		
014 *LBLB 21 12		070 x -35		
015 ST01 35 46		071 RCL2 36 02		
016 R+ -31		072 + -55		
017 ENT+ -21		073 ST05 35 05		
018 ENT+ -21		074 RTN 24		
019 RCL6 36 06		075 *LBL2 21 02		
020 x -35		076 PRTX -14		
021 ST06 35 06		077 RCL4 36 04		
022 R+ -31		078 PRTX -14		
023 RCL7 36 07		079 RCL5 36 05		
024 x -35		080 PRTX -14		
025 ST07 35 07		081 GT03 22 03		
026 2 02		082 *LBL4 21 04		
027 RTN 24		083 PRTX -14		
028 *LBLC 21 13		084 GT05 22 05		
029 RCL1 36 01		085 *LBLE 21 15		
030 ST04 35 04		086 F1? 16 23 01		
031 RCL2 36 02		087 GT01 22 01		
032 ST05 35 05		088 SF1 16 21 01		
033 1 01		089 1 01		
034 *LBL0 21 00		090 RTN 24		
035 F1? 16 23 01		091 *LBL1 21 01		
036 GT02 22 02		092 CF1 16 22 01		
037 R/S 51		093 0 00		
038 RCL4 36 04		094 RTN 24		
039 R/S 51		095 *LBLa 21 16 11		
040 RCL5 36 05		096 DSP9 -63 09		
041 R/S 51		097 0 00		
042 *LBL3 21 03		098 0 00		
043 RCL7 36 07		099 0 00		
044 + -55		100 0 00		
045 ST05 35 05		101 0 00		
046 R+ -31		102 0 00		
047 RCL6 36 06		103 0 00		
048 + -55		104 0 00		
049 ST04 35 04		105 0 00		
050 R+ -31		106 PSE 16 51		
051 1 01		107 GT0a 22 16 11		
052 + -55		108 RTN 24		
053 DSZ1 16 25 46				
054 GT00 22 00	110			
055 GT0a 22 16 11				
056 *LBLD 21 14				

REGISTERS

0	1	2	3	4	5	6	7	8	9
	X ₁	Y ₁	i-1	X	Y	ΔX	ΔY		
S0	S1	S2	S3	S4	S5	S6	S7	S8	S9
A	B	C	D	E	I	N, i			

Program Description I

Program Title Grid of Points: Calculates all points

Contributor's Name DAVID STEDMAN

Address 15950 OAKRIDGE ROAD

City MORGAN HILL, **State** CALIFORNIA **Zip Code** 95037

Program Description, Equations, Variables THIS PROGRAM CALCULATES THE X AND Y COORDINATES, ALL THE POINTS OF A GRID DEFINED AS FOLLOWS:

DATA: a) FIRST DIRECTION OF A GRID:

- ANGLE θ , WITH THE POSITIVE X AXIS
- ALGEBRAIC DISTANCE BETWEEN EACH POINT H, IN THIS DIRECTION.
- TOTAL NUMBER N, OF POINTS (INCLUDING THE FIRST ONE)

b) SECOND DIRECTION OF THE GRID:

- ANGLE θ_2 WITH THE POSITIVE X AXIS.
- ALGEBRAIC DISTANCE BETWEEN TWO POINTS H_2 IN THAT DIRECTION.
- TOTAL NUMBER N_2 OF POINTS (INCLUDING THE FIRST ONE)

c) STARTING POINT (NOTED 1) WITH COORDINATES X AND Y.

THE CALCULATION IS INCREMENTAL FROM POINT 1 TO POINT (N_1, N_2) FOR EACH POINT WE FIND:

- THE INDEX i, THE X_i and Y_i COORDINATES

AUTOMATIC STOP (THE END) IS INDICATED BY A FLASHING DISPLAY OF ZEROS.

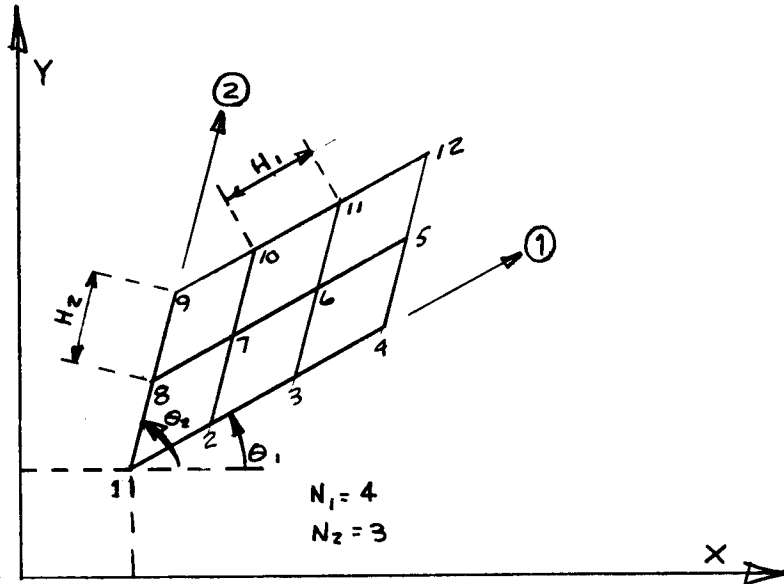
Operating Limits and Warnings

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

NEITHER HP NOR THE CONTRIBUTOR MAKES ANY EXPRESS OR IMPLIED WARRANTY OF ANY KIND WITH REGARD TO THIS PROGRAM MATERIAL, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. NEITHER HP NOR THE CONTRIBUTOR SHALL BE LIABLE FOR INCIDENTAL OR CONSEQUENTIAL DAMAGES IN CONNECTION WITH OR ARISING OUT OF THE FURNISHING, USE OR PERFORMANCE OF THIS PROGRAM MATERIAL.

Program Description II

Sketch(es)



Sample Problem(s)

$$\begin{aligned} \theta_1 &= 0^\circ, H_1 = 10, N_1 = 3 & \begin{bmatrix} X_1 = 10 \\ Y_1 = 10 \end{bmatrix} \\ \theta_2 &= 90^\circ, H_2 = 20, N_2 = 2 \end{aligned}$$

i	1	2	3	4	5	6
X_i	10.0000	20.0000	30.0000	30.0000	20.0000	10.0000
Y_i	10.0000	10.0000	10.0000	30.0000	30.0000	30.0000

Solution(s)

0 (↑) 10 (A) 90 (↑) 20 (B) 3 (↑) 2 (C) 10 (↑) 10 (D) (f) (A) (E) → 1.0000
 10.0000
 10.0000
 etc.

Reference(s)

39

[illegible]

97 Program Listing I

```

001 *LBLA      21 11
002 DSP4      -63 04
003 SF1       16 21 01
004 GSB6      23 16 15
005 ST01      35 01
006 R↓        -31
007 ST02      35 02
008 1         01
009 RTN       24
010 *LBLB     21 12
011 DSP4      -63 04
012 GSB6      23 16 15
013 ST03      35 03
014 R↓        -31
015 ST04      35 04
016 2         02
017 RTN       24
018 *LBLC     21 13
019 DSP4      -63 04
020 ST01      35 46
021 R↓        -31
022 1         01
023 -         -45
024 ST05      35 05
025 ST07      35 07
026 1         01
027 ST06      35 06
028 3         03
029 RTN       24
030 *LBLC     21 14
031 DSP4      -63 04
032 4         04
033 RTN       24
034 *LBLe     21 16 15
035 X*Y       -41
036 COS       42
037 LSTX      16-63
038 SIN       41
039 ENT↑      -21
040 R↑        16-31
041 x         -35
042 LSTX      16-63
043 R↑        16-31
044 x         -35
045 RTN       24
046 *LBLE     21 15
047 DSP4      -63 04
048 SPC       16-11
049 RCL6      36 06
050 GSB6      23 06
051 R↑        16-31
052 GSB6      23 06
053 R↑        16-31
054 GSB6      23 06
055 X*Y       -41
056 R↑        16-31

```

COMMENTS

```

057 R↑        16-31
058 *LBL2     21 02
059 F1?      16 23 01
060 GT01      22 01
061 *LBL3     21 03
062 GSB6      23 16 12
063 RCL1      36 01
064 -         -45
065 GSB6      23 06
066 X*Y       -41
067 RCL2      36 02
068 -         -45
069 GSB6      23 06
070 RCL7      36 07
071 1         01
072 -         -45
073 ST07      35 07
074 0         00
075 X*Y?     16-32
076 GT03      22 03
077 SF1      16 21 01
078 R↓        -31
079 RCL5      36 05
080 ST07      35 07
081 *LBL4     21 04
082 DSZ       16 25 46
083 GT05      22 05
084 0         00
085 GT08      22 08
086 *LBL5     21 05
087 GSB6      23 16 12
088 RCL3      36 03
089 +         -55
090 GSB6      23 06
091 X*Y       -41
092 RCL4      36 04
093 +         -55
094 GSB6      23 06
095 ENT↑      -21
096 ENT↑      -21
097 GT02      22 02
098 *LBL1     21 01
099 GSB6      23 16 12
100 RCL1      36 01
101 +         -55
102 GSB6      23 06
103 X*Y       -41
104 RCL2      36 02
105 +         -55
106 GSB6      23 06
107 RCL7      36 07
108 1         01
109 -         -45
110 ST07      35 07
111 0         00
112 X*Y?     16-32

```

COMMENTS

REGISTERS

0	1	2	3	4	5	6	7	8	9
	ΔX_1	ΔY_1	ΔX_2	ΔY_2	$N_1 - 1$	i	$N_1 - 1$	N_2	
S0	S1	S2	S3	S4	S5	S6	S7	S8	S9
A	B	C	D	E	I	DSZ			

97 Program Listing II

41

STEP	KEY ENTRY	KEY CODE	COMMENTS	STEP	KEY ENTRY	KEY CODE	COMMENTS
113	GT01	22 01					
114	CF1	16 22 01		170			
115	R↓	-31					
116	RCL5	36 05					
117	ST07	35 07					
118	GT04	22 04					
119	*LBL6	21 16 12					
120	R↓	-31					
121	R↓	-31					
122	XZY	-41					
123	RCL6	36 06		180			
124	1	01					
125	+	-55					
126	ST06	35 06					
127	GSB6	23 06					
128	R↓	-31					
129	RTN	24					
130	*LBLa	21 16 11					
131	F0?	16 23 00					
132	GT07	22 07					
133	SF0	16 21 00		190			
134	CLX	-51					
135	1	01					
136	RTN	24					
137	*LBL7	21 07					
138	CF0	16 22 00					
139	CLX	-51					
140	0	00					
141	RTN	24					
142	*LBL6	21 06		200			
143	F0?	16 23 00					
144	PRTX	-14					
145	F0?	16 23 00					
146	RTN	24					
147	R/S	51					
148	RTN	24					
149	*LBL8	21 08					
150	DSP9	-63 09					
151	0	00					
152	0	00					
153	0	00		210			
154	0	00					
155	0	00					
156	0	00					
157	0	00					
158	0	00					
159	0	00					
160	PSE	16 51					
161	GT08	22 08					
162	RTN	24					
163	R/S	51		220			

LABELS					FLAGS		SET STATUS		
A θ_1, H_1	B θ_2, H_2	C N_1, N_2	D X_1, Y_1	E $P_1 \rightarrow P_n$	0 AUTO TOGGLE	E FLAGS		TRIG	DISP
a AUTO?	b	c	d	e	1 USED	0 ON OFF	DEG ☒	FIX ☒	
0	1 X	2 X	3 X	4 X	2	1 ☐	GRAD ☐	SCI ☐	
5 X	6 PRINT/RS	7 X	8 END DISPLAY	9	3	2 ☐	RAD ☐	ENG ☐	
						3 ☐		n 4	

Program Description I

Program Title Grid of Points: Calculate Discrete Points

Contributor's Name DAVID STEDMAN

Address 15950 OAKRIDGE ROAD

City MORGAN HILL,

State CALIFORNIA

Zip Code 95037

Program Description, Equations, Variables THIS PROGRAM COMPLEMENTS "SOLUTION TO GEOMETRIC PROBLEMS, PART #7," "GRID OF POINTS: CALCULATE ALL POINTS". IT ALLOWS THE CALCULATION OF SPECIFIED POINTS OF A GRID DEFINED AS FOLLOWS:

DATA:

a) FIRST DIRECTION:

- ANGLE θ_1 , (RELATED TO POSITIVE X AXIS).
- DISTANCE BETWEEN EACH POINT H_1 , IN THIS DIRECTION.

b) SECOND DIRECTION:

- ANGLE θ_2
- AND H_2

c) STARTING POINT (ORIGIN OF THE GRID): 11

WE GIVE X_{11} AND Y_{11} .

FORMULAS: THE FIRST DIRECTION REPRESENTS THE LINES OF THE SECOND COLUMNS.

$$X_{ij} = X_1 + (j-1) \Delta X_1 + (i-1) \Delta X_2$$

$$Y_{ij} = Y_1 + (j-1) \Delta Y_1 + (i-1) \Delta Y_2$$

$$\Delta X_1 = H_1 \cos \theta_1$$

$$\Delta Y_1 = H_1 \sin \theta_1$$

$$\Delta X_2 = H_2 \cos \theta_2$$

$$\Delta Y_2 = H_2 \sin \theta_2$$

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

NEITHER HP NOR THE CONTRIBUTOR MAKES ANY EXPRESS OR IMPLIED WARRANTY OF ANY KIND WITH REGARD TO THIS PROGRAM MATERIAL, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. NEITHER HP NOR THE CONTRIBUTOR SHALL BE LIABLE FOR INCIDENTAL OR CONSEQUENTIAL DAMAGES IN CONNECTION WITH OR ARISING OUT OF THE FURNISHING, USE OR PERFORMANCE OF THIS PROGRAM MATERIAL.

Program Description II

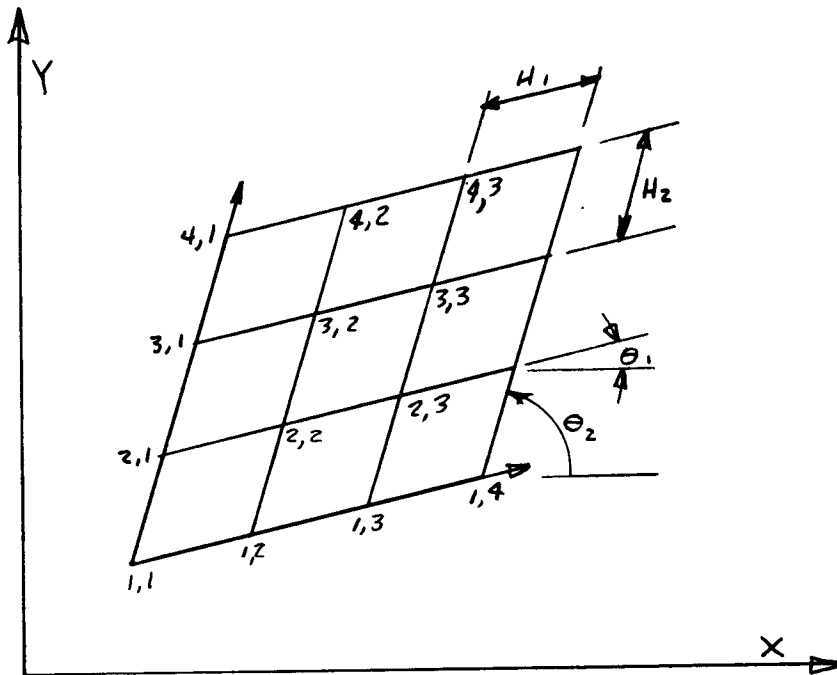
EXAMPLE :

FIRST DIRECTION $\theta_1 = 0^\circ$, $H_1 = 10$

SECOND DIRECTION $\theta_2 = 90^\circ$, $H_2 = 20$

$X_{11} = 0$, $Y_{11} = 0$

i,j	1,1	1,2	2,1	-1,3
X_{ij}	0.0000	10.0000	0.0000	20.0000
Y_{ij}	0.0000	0.0000	20.0000	-40.0000



0 (↑) 10 (A) 90 (↑) 20 (B) 0 (↑) 0 (C) 1 (↑) 2 (D) -----> 10.0000

R/S-----> 0.0000

etc.

Reference(s)

97Program Listing I

45

```

001 *LBLA 21 11
002 GSB 23 16 15
003 ST01 35 01
004 R↓ -31
005 ST02 35 02
006 1 01
007 RTN 24
008 *LBLB 21 12
009 GSB 23 16 15
010 ST03 35 03
011 R↓ -31
012 ST06 35 06
013 2 02
014 RTN 24
015 *LBLC 21 16 15
016 X↔Y -41
017 COS 42
018 LSTX 16-63
019 SIN 41
020 ENT↑ -21
021 R↑ 16-31
022 x -35
023 LSTX 16-63
024 R↑ 16-31
025 x -35
026 RTN 24
027 *LBLC 21 13
028 ST05 35 05
029 R↓ -31
030 ST04 35 04
031 3 03
032 RTN 24
033 *LBLC 21 14
034 1 01
035 - -45
036 ST08 35 08
037 R↓ -31
038 1 01
039 - -45
040 ST07 35 07
041 RCL8 36 08
042 RCL1 36 01
043 x -35
044 RCL7 36 07
045 RCL3 36 03
046 x -35
047 + -55
048 RCL4 36 04
049 + -55
050 GSB1 23 01
051 RCL8 36 08
052 RCL2 36 02
053 x -35
054 RCL7 36 07
055 RCL6 36 06
056 x -35
    
```

COMMENTS

STEP

KEY ENTRY

KEY CODE

COMMENTS

```

057 + -55
058 RCL5 36 05
059 + -55
060 RTN 24
061 *LBL1 21 01
062 F0? 16 23 00
063 PRTX -14
064 F0? 16 23 00
065 RTN 24
066 R/S 51
067 RTN 24
068 *LBLE 21 15
069 F0? 16 23 00
070 GT02 22 02
071 SF0 16 21 00
072 1 01
073 RTN 24
074 *LBL2 21 02
075 CF0 16 22 00
076 0 00
077 RTN 24
    
```

080

090

LABELS

A	B	C	D	E
0 ₁ H ₁	0 ₂ H ₂	X ₁ Y ₁	i,j→X,Y	AUTO?
a	b	c	d	e
0	1 USED	2 USED	3	4
5	6	7	8	9

	0 AUTO TOGGLE	SET STATUS		
		FLAGS	TRIG	DISP
		ON OFF		
	1	0 ☐ ☒	DEG ☒	FIX ☒
	2	1 ☐ ☒	GRAD ☐	SCI ☐
110	3	2 ☐ ☒	RAD ☐	ENG ☐
		3 ☐ ☒		n-4

REGISTERS

0	1 ΔX ₁	2 ΔY ₁	3 ΔX ₂	4 X ₁₁	5 Y ₁₁	6 ΔY ₂	7 i-1	8 j-1	9
S0	S1	S2	S3	S4	S5	S6	S7	S8	S9
A	B	C	D	E	I				

Program Description I

Program Title Tangent Circle to Two Straight Lines with a Given Radius

Contributor's Name David Stedman

Address 15950 Oakridge Road

City Morgan Hill,

State California

Zip Code 95037

Program Description, Equations, Variables THIS PROBLEM CALCULATES THE X AND Y COORDINATES OF THE CENTER OF A CIRCLE WITH A GIVEN RADIUS. THIS CIRCLE BEING TANGENT TO TWO GIVEN STRAIGHT LINES. IN THE MORE GENERAL CASE, THERE ARE FOUR CENTER SOLUTIONS TO THIS PROBLEM.

INPUT SUCCESSIVELY:

- THE RADIUS OF THE CIRCLE TO BE DETERMINED: R_f [A]
- EACH OF THE STRAIGHT LINES IN THE FOLLOWING MANNER:
DEFINE THE STRAIGHT LINE BY POINT AND ANGLE, THE INDICATED
POSITION OF THE CIRCLE TO BE DETERMINED BY REFERENCE TO
THE STRAIGHT LINE:

[B]: CIRCLE ABOVE THE STRAIGHT LINES

[C]: CIRCLE BELOW THE STRAIGHT LINES

[D]: CIRCLE TO THE LEFT OF THE STRAIGHT LINES

[E]: CIRCLE TO THE RIGHT OF THE STRAIGHT LINES

THESE MODIFIERS ALLOW THE SHIFTING OF THE TWO INITIAL STRAIGHT LINES,
THE CALCULATION IS THEN THE ONE OF THE INTERSECTION OF TWO STRAIGHT LINES.

LINE 1 = $[X_1, Y_1, \theta_1]$

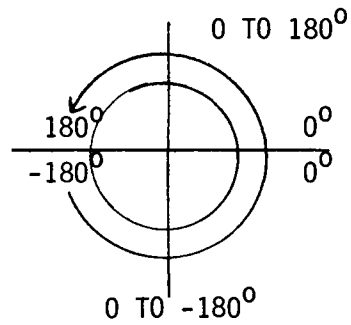
(X_i, Y_i) SHIFTED POINTS

LINE 2 = $[X_2, Y_2, \theta_2]$

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

NEITHER HP NOR THE CONTRIBUTOR MAKES ANY EXPRESS OR IMPLIED WARRANTY OF ANY KIND WITH REGARD TO THIS PROGRAM MATERIAL, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. NEITHER HP NOR THE CONTRIBUTOR SHALL BE LIABLE FOR INCIDENTAL OR CONSEQUENTIAL DAMAGES IN CONNECTION WITH OR ARISING OUT OF THE FURNISHING, USE OR PERFORMANCE OF THIS PROGRAM MATERIAL.

ALL ANGLES MUST BE INPUT FOLLOWING THESE CONVENTIONS:



FORMULAS USED:

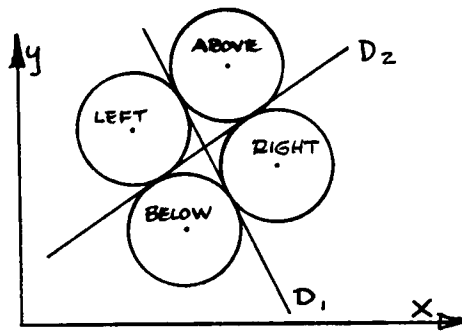
$$X = \frac{(Y_2 - Y_1) \cos \theta_1 \cos \theta_2 + X_1 \sin \theta_1 \cos \theta_2 - X_2 \sin \theta_2 \cos \theta_1}{\sin (\theta_1 - \theta_2)}$$

$$Y = Y_1 + (X - X_1) \tan \theta_1$$

$$Y = Y_2 + (X - X_2) \tan \theta_2$$

Program Description II

Sketch(es)



Sample Problem(s)

$$D_1 = [10, 20, 30^\circ]$$

$$Rf = 10$$

$$D_2 = [-20, 30, -60^\circ]$$

THE PROGRAM BEING EXECUTED FOUR TIMES WILL YIELD:

POSITION OF CIRCLE		X	Y
D ₁	D ₂		
ABOVE B	B	-4.5096	23.1699
BELOW C	C	-11.8301	-4.1506
LEFT D	D	-21.8301	13.1699
RIGHT E	E	5.4904	5.8494

Solution(s)

10 (A) 10 (↑) 20 (↑) 30 (B) 20 (CHS) (↑) 30 (↑) 60 (CHS)

(B) (F) (A) -----> -4.5096

(F) (B) -----> 23.1699

Reference(s)

49

[illegible]

97 Program Listing I

STEP	KEY ENTRY	KEY CODE	COMMENTS				COMMENTS		
001	*LBLA	21 11		057	x	-35			
002	ST08	35 08		058	RCL6	36 06			
003	RTN	24		059	COS	42			
004	*LBLB	21 12		060	ST08	35 08			
005	RCL8	36 08		061	x	-35			
006	GT01	22 01		062	RCL1	36 01			
007	*LBLC	21 13		063	RCL8	36 08			
008	RCL8	36 08		064	x	-35			
009	CHS	-22		065	RCL3	36 03			
010	*LBL1	21 01		066	SIN	41			
011	X $\div$ Y	-41		067	x	-35			
012	F1?	16 23 01		068	+	-55			
013	GT02	22 02		069	RCL4	36 04			
014	ST03	35 03		070	RCL7	36 07			
015	X $\div$ Y	-41		071	x	-35			
016	$\rightarrow$ R	44		072	RCL6	36 06			
017	X $\div$ Y	-41		073	SIN	41			
018	R $\downarrow$	-31		074	x	-35			
019	+	-55		075	-	-45			
020	ST02	35 02		076	RCL3	36 03			
021	R $\downarrow$	-31		077	RCL6	36 06			
022	X $\div$ Y	-41		078	-	-45			
023	-	-45		079	SIN	41			
024	ST01	35 01		080	$\div$	-24			
025	SF1	16 21 01		081	ST07	35 07			
026	RTN	24		082	RTN	24			
027	*LBL2	21 02		083	*LBL6	21 16 12			
028	ST06	35 06		084	RCL3	36 03			
029	X $\div$ Y	-41		085	ABS	16 31			
030	$\rightarrow$ R	44		086	9	09			
031	X $\div$ Y	-41		087	0	00			
032	R $\downarrow$	-31		088	X $\div$ Y	-41			
033	+	-55		089	GT03	22 03			
034	ST05	35 05		090	RCL7	36 07			
035	R $\downarrow$	-31		091	RCL1	36 01			
036	X $\div$ Y	-41		092	-	-45			
037	-	-45		093	RCL3	36 03			
038	ST04	35 04		094	TAN	43			
039	CF1	16 22 01		095	x	-35			
040	RTN	24		096	RCL2	36 02			
041	*LBLD	21 14		097	GT04	22 04			
042	X $\times$ 0?	16-45		098	*LBL3	21 03			
043	GT0C	22 13		099	RCL7	36 07			
044	GT0B	22 12		100	RCL4	36 04			
045	*LBLE	21 15		101	-	-45			
046	X $\times$ 0?	16-45		102	RCL6	36 06			
047	GT0B	22 12		103	TAN	43			
048	GT0C	22 13		104	x	-35			
049	RTN	24		105	RCL5	36 05			
050	*LBL6	21 16 11		106	*LBL4	21 04			
051	RCL5	36 05		107	+	-55			
052	RCL2	36 02		108	ST05	35 05			
053	-	-45		109	RCL7	36 07			
054	RCL3	36 03		110	ST04	35 04			
055	COS	42		111	R $\downarrow$	-31			
056	ST07	35 07		112	SPC	16-11			
REGISTERS									
0	1	2	3	4	5	6	7	8	9
	X' 1	Y' 1	θ_1	X' 2	Y' 2/Y	θ_2	COS θ_1	Rf/COS θ_2	
S0	S1	S2	S3 1	S4	S5	S6 2	S7 1	S8	S9
A	B	C	D	E	I				

51

[illegible]

Program Description I

Program Title **DISTANCE BETWEEN LINES IN SPACE**

Contributor's Name **ROBERT H. MANSFIELD**

Address **1411 E. MISSION**

City **SPOKANE**

State **WASHINGTON** Zip Code **99202**

Program Description, Equations, Variables **GIVEN TWO LINES, EACH DEFINED BY ANY TWO POINTS, PROGRAM CALCULATES SHORTEST DISTANCE BETWEEN THE TWO LINES. (THIS PROGRAM WAS WRITTEN TO DETERMINE THE CLEARANCE BETWEEN ELECTRICAL DISTRIBUTION CIRCUITS AND GUY WIRES OR SUPPORTING STRUCTURES.)**

PROGRAM TAKES LINES DEFINED BY THE TWO-POINT FORM,

Two-point form:
$$\frac{x - x_1}{x_2 - x_1} = \frac{y - y_1}{y_2 - y_1} = \frac{z - z_1}{z_2 - z_1}$$

CHANGES THEM TO THE POINT-DIRECTION FORM,

Point-direction form:
$$\frac{x - x_1}{a} = \frac{y - y_1}{b} = \frac{z - z_1}{c}$$

AND THE SHORTEST DISTANCE (D) IS CALCULATED BY:

$$D = \pm \frac{\begin{vmatrix} x_2 - x_1 & y_2 - y_1 & z_2 - z_1 \\ a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \end{vmatrix}}{\sqrt{\begin{vmatrix} b_1 & c_1 \\ b_2 & c_2 \end{vmatrix}^2 + \begin{vmatrix} c_1 & a_1 \\ c_2 & a_2 \end{vmatrix}^2 + \begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix}^2}}$$

Operating Limits and Warnings

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

NEITHER HP NOR THE CONTRIBUTOR MAKES ANY EXPRESS OR IMPLIED WARRANTY OF ANY KIND WITH REGARD TO THIS PROGRAM MATERIAL, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. NEITHER HP NOR THE CONTRIBUTOR SHALL BE LIABLE FOR INCIDENTAL OR CONSEQUENTIAL DAMAGES IN CONNECTION WITH OR ARISING OUT OF THE FURNISHING, USE OR PERFORMANCE OF THIS PROGRAM MATERIAL.

Program Description II

Sketch(es)

Sample Problem(s) GIVEN TWO LINES IN THREE-DIMENSIONAL SPACE:

LINE #1 DEFINED BY POINTS $x_1, y_1, z_1 = 30, 14, 10$ AND
 $x'_1, y'_1, z'_1 = 0, 46, 10$;

LINE #2 DEFINED BY POINTS $x_2, y_2, z_2 = 124, 50, -30$ AND
 $x'_2, y'_2, z'_2 = 0, 36, 16$.

CALCULATE THE SHORTEST DISTANCE BETWEEN THE TWO LINES.

CHANGE LINE #1 BY MOVING x'_1, y'_1, z'_1 TO 5, 48, 7 AND
 REPEAT THE DISTANCE CALCULATION.

Solution(s) KEYSTROKES:

30↑14↑10[A] 0↑46↑10[B] 124↑50↑30[CHS][C] 0↑36↑16[D][E]→2.59
 (SHORTEST DISTANCE BETWEEN LINES IS 2.59 UNITS.)

CHANGE LINE #1 AND RECALCULATE DISTANCE:

5↑48↑7[B][E]→3.02
 (SHORTEST DISTANCE IS NOW 3.02 UNITS.)

Reference(s) HANDBOOK OF TABLES FOR MATHEMATICS, THIRD EDITION,
 SAMUEL M. SELBY, PUBLISHED BY THE CHEMICAL RUBBER CO.
 1967, PAGE 509.

[illegible]

Hewlett-Packard Software

In terms of power and flexibility, the problem-solving potential of the Hewlett-Packard line of fully programmable calculators is nearly limitless. And in order to see the practical side of this potential, we have several different types of software to help save you time and programming effort. Every one of our software solutions has been carefully selected to effectively increase your problem-solving potential. Chances are, we already have the solutions you're looking for.

Application Pacs

To increase the versatility of your fully programmable Hewlett-Packard calculator, HP has an extensive library of "Application Pacs". These programs transform your HP-67 and HP-97 into specialized calculators in seconds. Each program in a pac is fully documented with commented program listing, allowing the adoption of programming techniques useful to each application area. The pacs contain 20 or more programs in the form of prerecorded cards, a detailed manual, and a program card holder. Every Application Pac has been designed to extend the capabilities of our fully programmable models to increase your problem-solving potential.

You can choose from:

Statistics
Mathematics
Electrical Engineering
Business Decisions
Clinical Lab and Nuclear Medicine

Mechanical Engineering
Surveying
Civil Engineering
Navigation
Games

Users' Library

The main objective of our Users' Library is dedicated to making selected program solutions contributed by our HP-67 and HP-97 users available to you. By subscribing to our Users' Library, you'll have at your fingertips, literally hundreds of different programs. No longer will you have to: research the application; program the solution; debug the program; or complete the documentation. Simply key your program to obtain your solution. In addition, programs from the library may be used as a source of programming techniques in your application area.

A one-year subscription to the Library costs \$9.00. You receive: a catalog of contributed programs; catalog updates; and coupons for three programs of your choice (a \$9.00 value).

Users' Library Solutions Books

Hewlett-Packard recently added a unique problem-solving contribution to its existing software line. The new series of software solutions are a collection of programs provided by our programmable calculator users. Hewlett-Packard has currently accepted over 6,000 programs for our Users' Libraries. The best of these programs have been compiled into 40 Library Solutions Books covering 39 application areas (including two game books).

Each of the Books, containing up to 15 programs without cards, is priced at \$10.00, a savings of up to \$35.00 over single copy cost.

The Users' Library Solutions Books will compliment our other applications of software and provide you with a valuable new tool for program solutions.

Options/Technical Stock Analysis
Portfolio Management/Bonds & Notes
Real Estate Investment
Taxes
Home Construction Estimating
Marketing/Sales
Home Management
Small Business
Antennas
Butterworth and Chebyshev Filters
Thermal and Transport Sciences
EE (Lab)
Industrial Engineering
Aeronautical Engineering
Control Systems
Beams and Columns
High-Level Math
Test Statistics
Geometry
Reliability/QA

Medical Practitioner
Anesthesia
Cardiac
Pulmonary
Chemistry
Optics
Physics
Earth Sciences
Energy Conservation
Space Science
Biology
Games
Games of Chance
Aircraft Operation
Aviation
Calendars
Photo Dark Room
COGO-Surveying
Astrology
Forestry

GEOMETRY

These programs calculate basic geometry problems, mostly plane geometry. Calculations include points, lines, circles, intersections, distances, angles, etc.

SINE PLATE SOLUTIONS

V NOTCHES AND LONG RADII

INTERNAL AND EXTERNAL TAPERS

POINTS OF TANGENCY WITH CIRCLES AND ARCS

LINE-LINE INTERSECTION/GRID POINTS

POINTS ON A STRAIGHT LINE

GRID OF POINTS: CALCULATES ALL POINTS

GRID OF POINTS: CALCULATES DISCRETE POINTS

TANGENT CIRCLE TO TWO STRAIGHT LINES WITH A GIVEN RADIUS

DISTANCE BETWEEN LINES IN SPACE



1000 N.E. Circle Blvd., Corvallis, OR 97330

Reorder No. 00097-14007 Printed in U.S.A. 00097-90182
Revision B 1-78